

3-D Finite-Element Modelling of Magnetotelluric Data With a Static Divergence Correction

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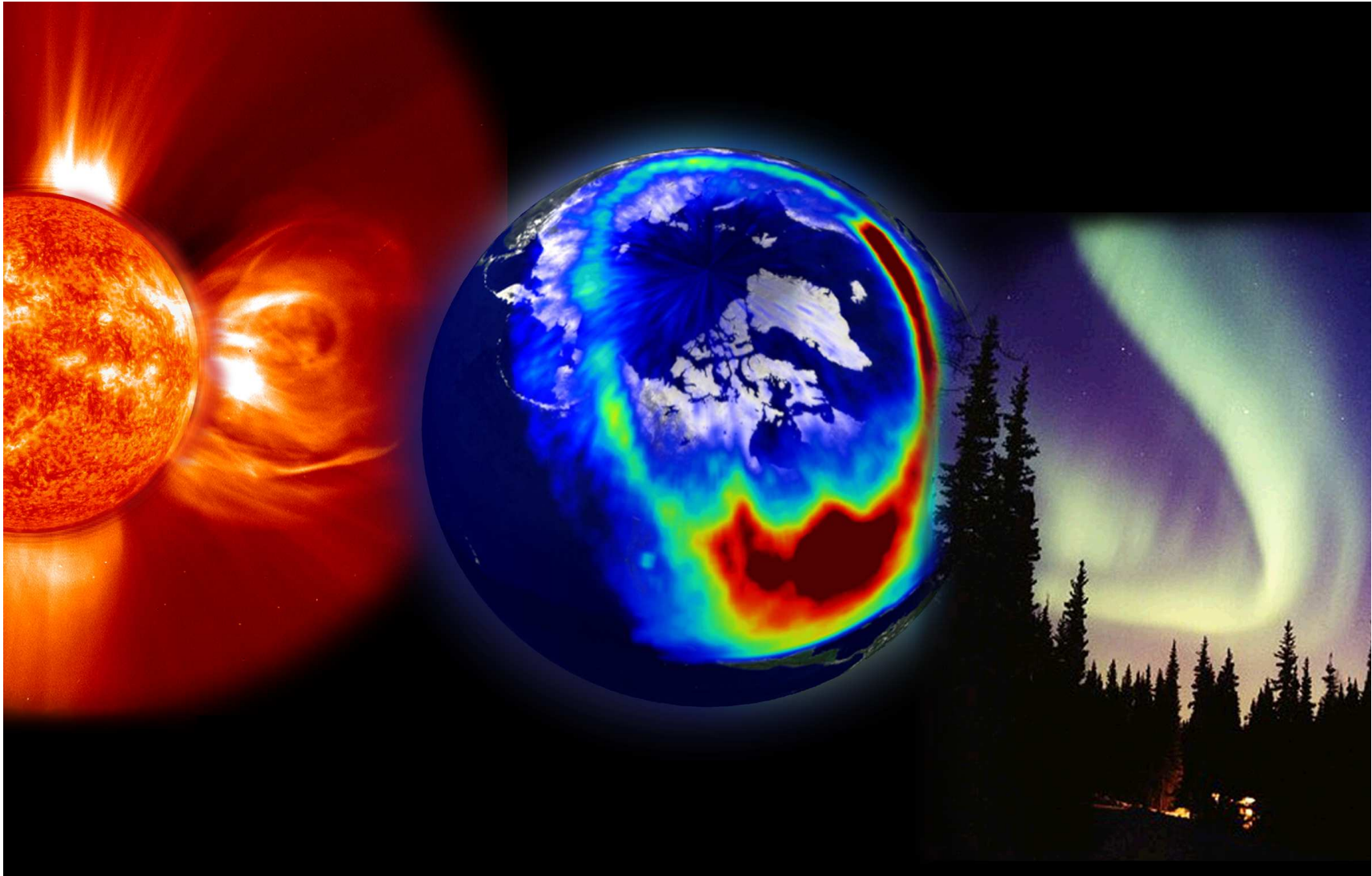
Acknowledgments

- ★ Marion Miensopest, Dublin Institute of Advanced Studies, and National University of Ireland, Galway.



National University of Ireland, Galway
Ollscoil na hÉireann, Gaillimh

The Magnetotelluric Method



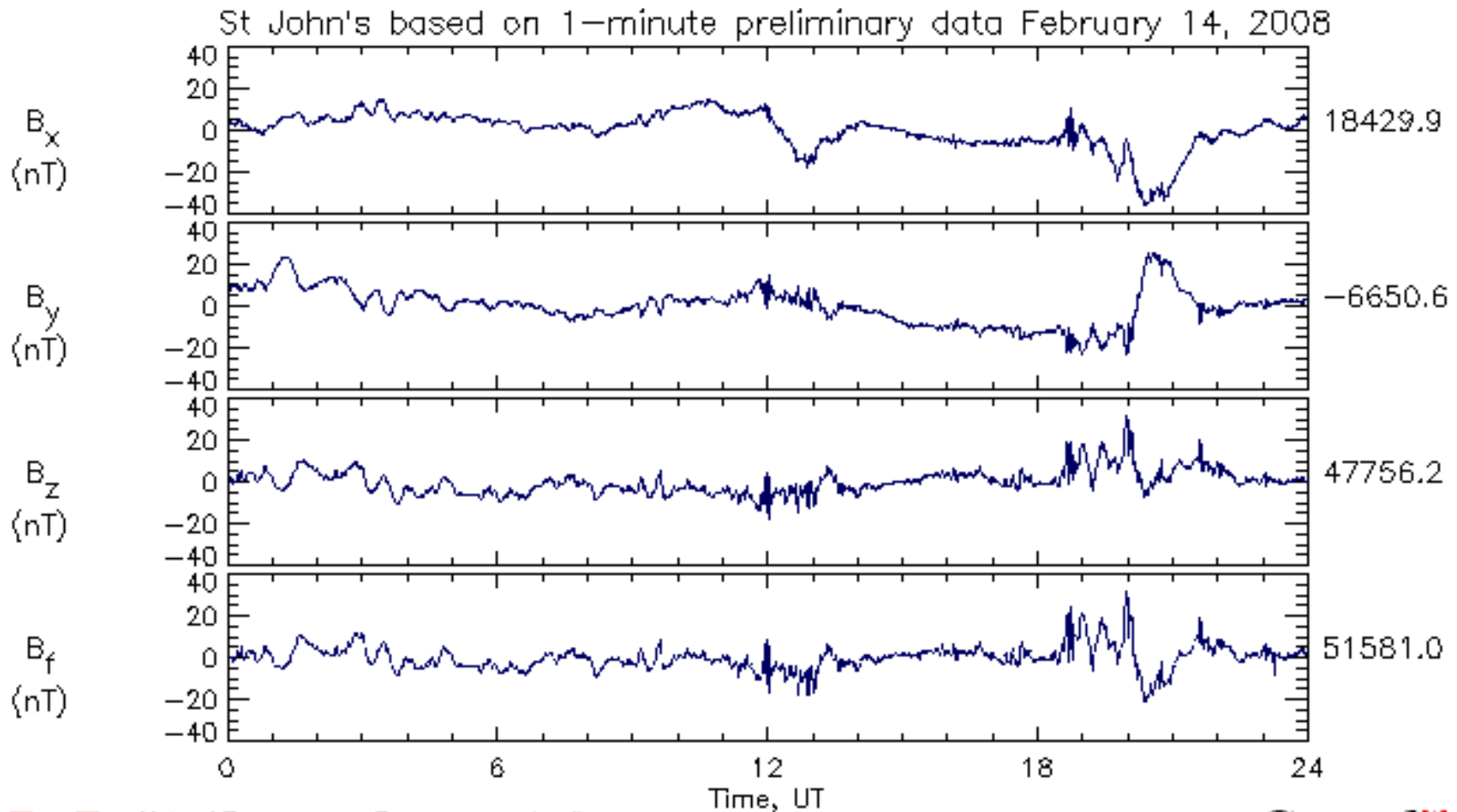
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The Magnetotelluric Method



The Internet

The Magnetotelluric Method

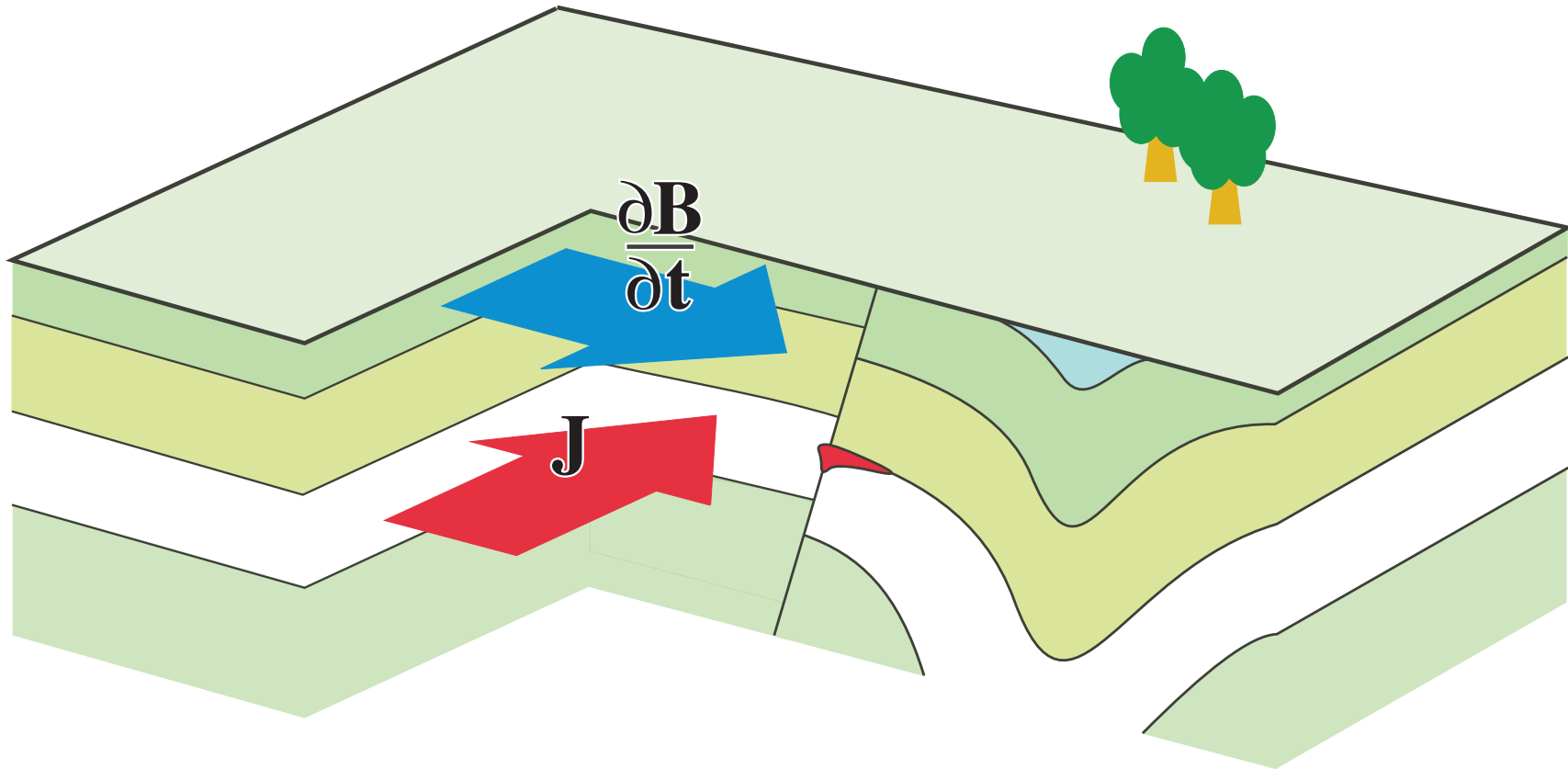


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The Magnetotelluric Method



Measure \mathbf{E} and \mathbf{H} . Their ratio contains information about the electrical conductivity of the subsurface.

Standard Finite-Element Modelling

Fundamental equations:

$$\nabla \times \mathbf{E} = i\omega\mu_0\mathbf{H} \quad \nabla \times \mathbf{H} = \mathbf{J}$$

$$\mathbf{J} = \sigma\mathbf{E}, \quad \sigma = \sigma(\mathbf{r})$$

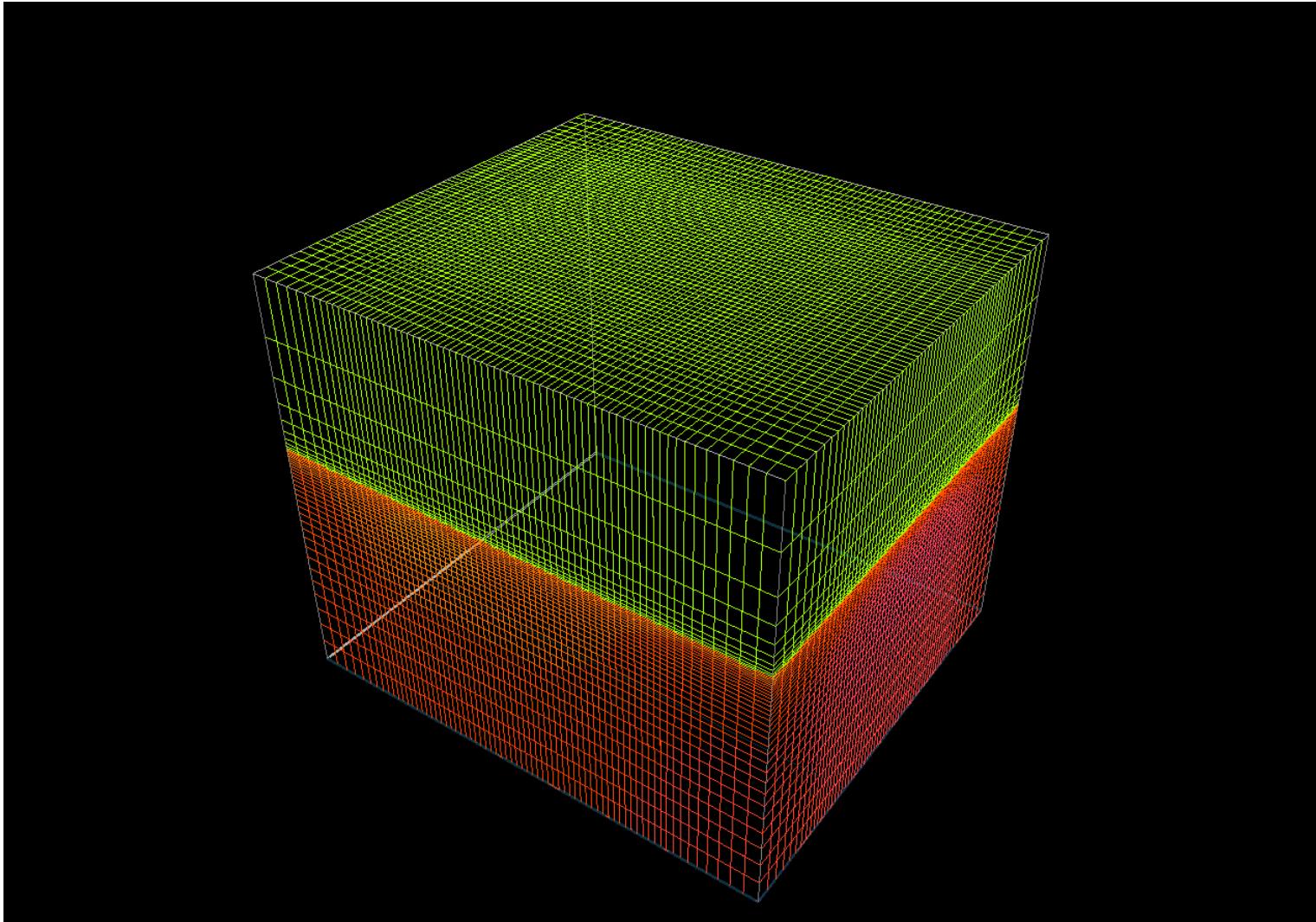
(Quasi-static)

PDE for electric field:

$$\nabla \times \nabla \times \mathbf{E} - i\omega\mu_0\sigma\mathbf{E} = 0$$

Standard Finite-Element Modelling

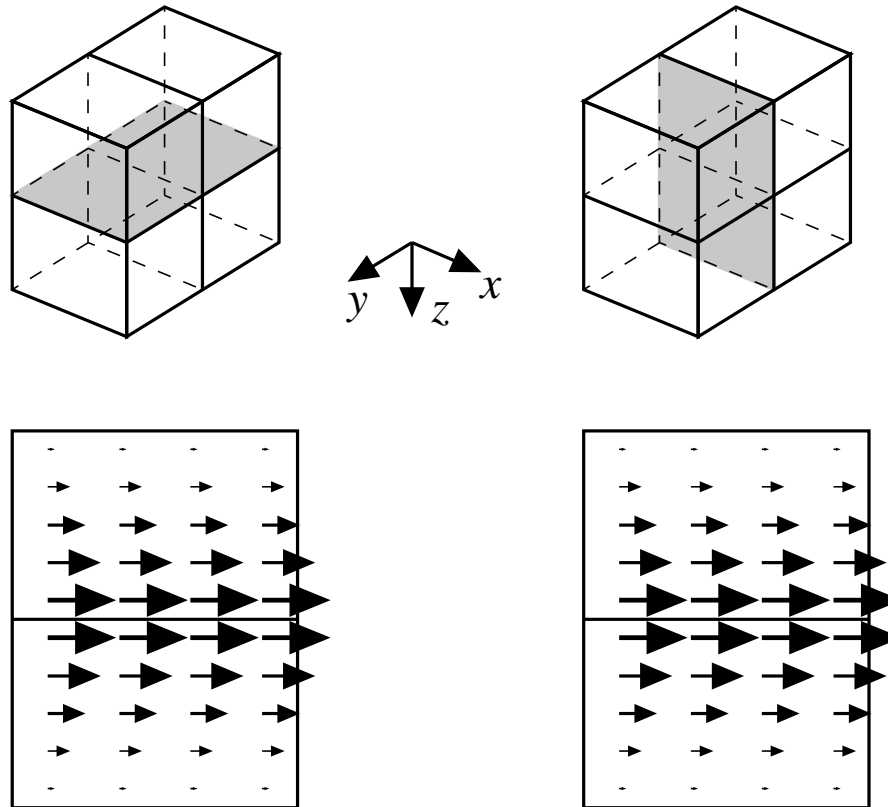
Discretization:



Standard Finite-Element Modelling

Edge-element basis functions:

$$\tilde{\mathbf{E}} = \sum_{j=1}^N \tilde{E}_j \mathbf{v}_j$$



Standard Finite-Element Modelling

Constructing system of equations:

$$\nabla \times \nabla \times \mathbf{E} - i\omega\mu_0\sigma\mathbf{E} = 0$$

$$\sum_{j=1}^N \tilde{E}_j \left\{ \nabla \times \nabla \times \mathbf{v}_j - i\omega\mu_0\sigma\mathbf{v}_j \right\} - \mathbf{R} = 0$$

$$\sum_{j=1}^N \tilde{E}_j \left\{ \int_V \mathbf{v}_i \cdot \nabla \times \nabla \times \mathbf{v}_j dv - i\omega\mu_0 \int_V \sigma \mathbf{v}_i \cdot \mathbf{v}_j dv \right\} = 0$$

$$\sum_{j=1}^N \tilde{E}_j \left\{ \int_V (\nabla \times \mathbf{v}_i) \cdot (\nabla \times \mathbf{v}_j) dv - i\omega\mu_0 \int_V \sigma \mathbf{v}_i \cdot \mathbf{v}_j dv \right\} = 0$$

$$(i = 1, \dots, N)$$

Standard Finite-Element Modelling

Constructing system of equations (continued):

- Determine formulae for $\int_V (\nabla \times \mathbf{v}_i) \cdot (\nabla \times \mathbf{v}_j) dv$ and $\int_V \sigma \mathbf{v}_i \cdot \mathbf{v}_j dv$ (which depend only on i, j, σ and cell dimensions).
- Assemble the matrix equation:

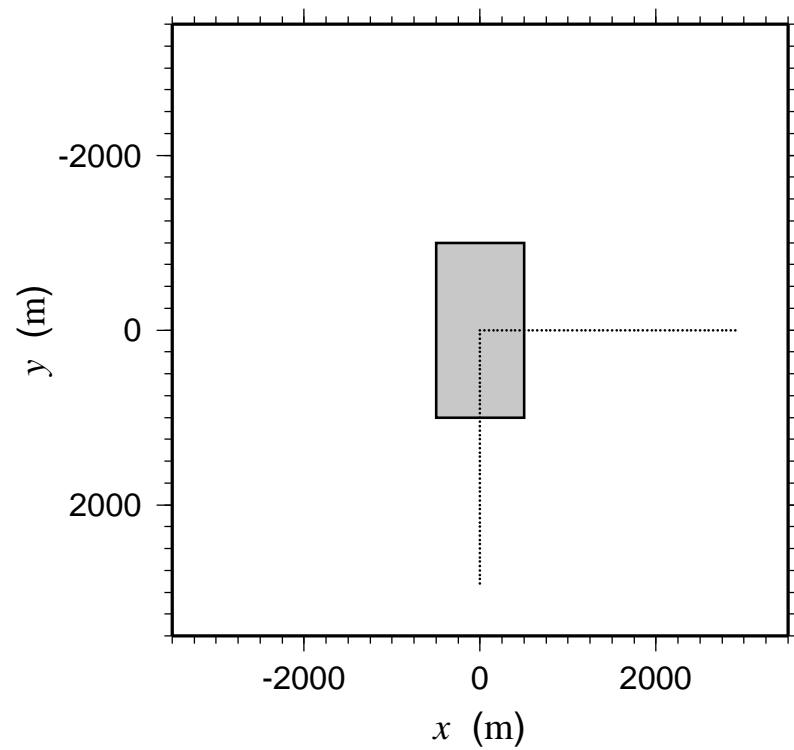
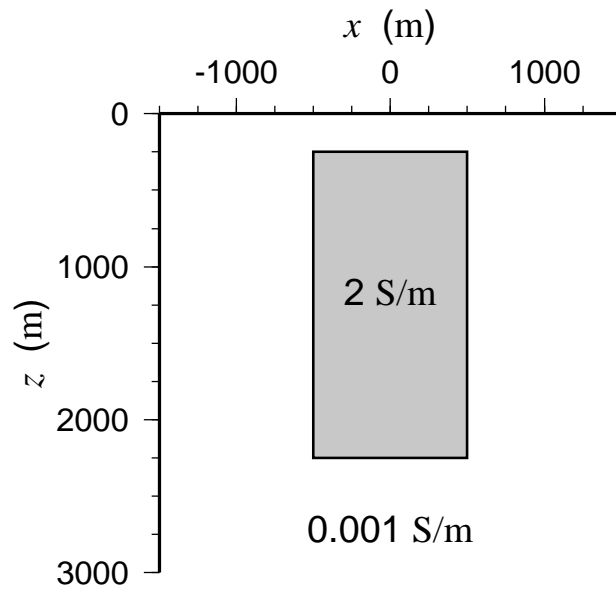
$$\mathbf{M} \tilde{\mathbf{E}} = 0$$

(separating real and imaginary parts).

- Incorporate Dirichlet boundary conditions into the matrix equation.
- Solve using ILU preconditioned BCGSTAB, GMRES, etc. (Sparskit).

Standard Finite-Element Modelling: Results

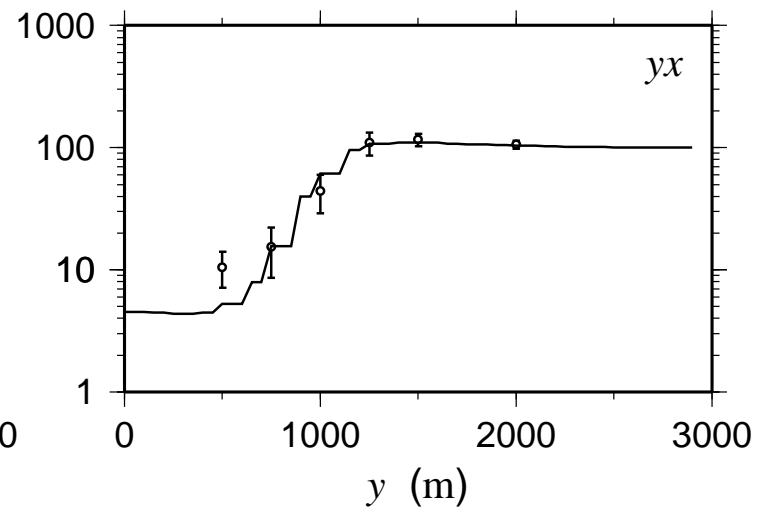
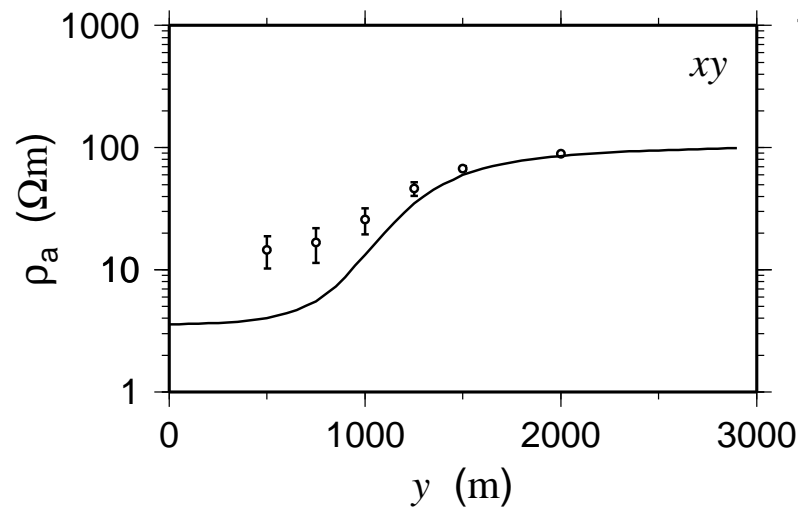
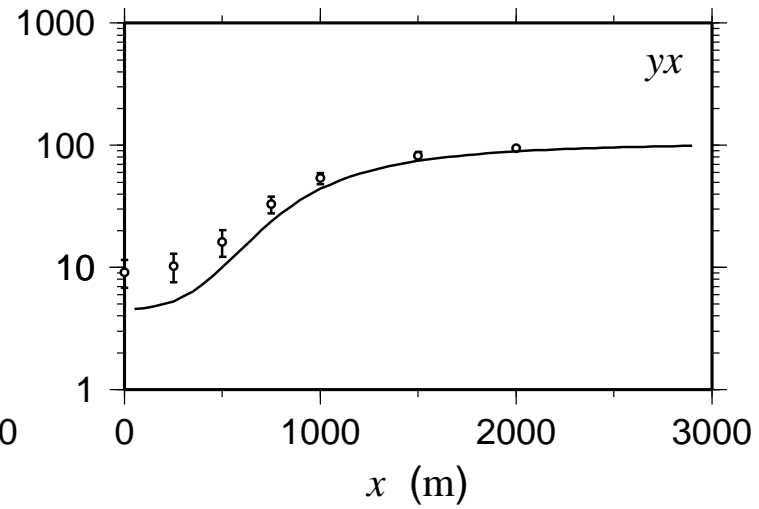
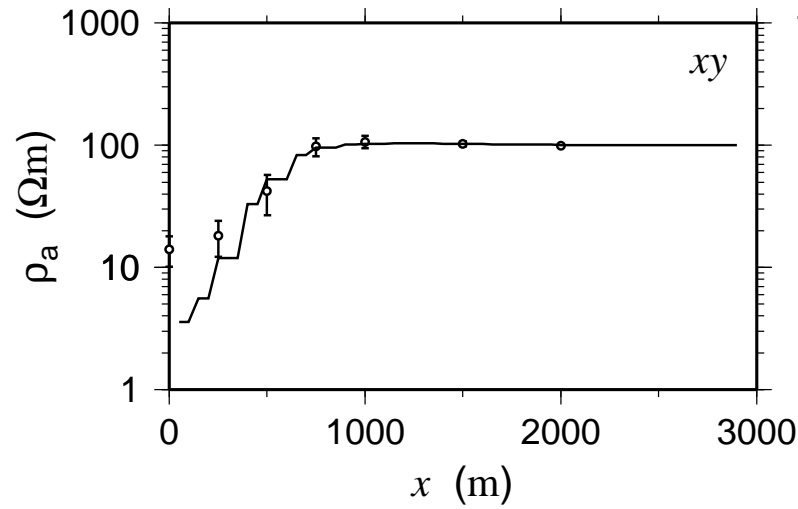
COMMEMI 3D-1A:



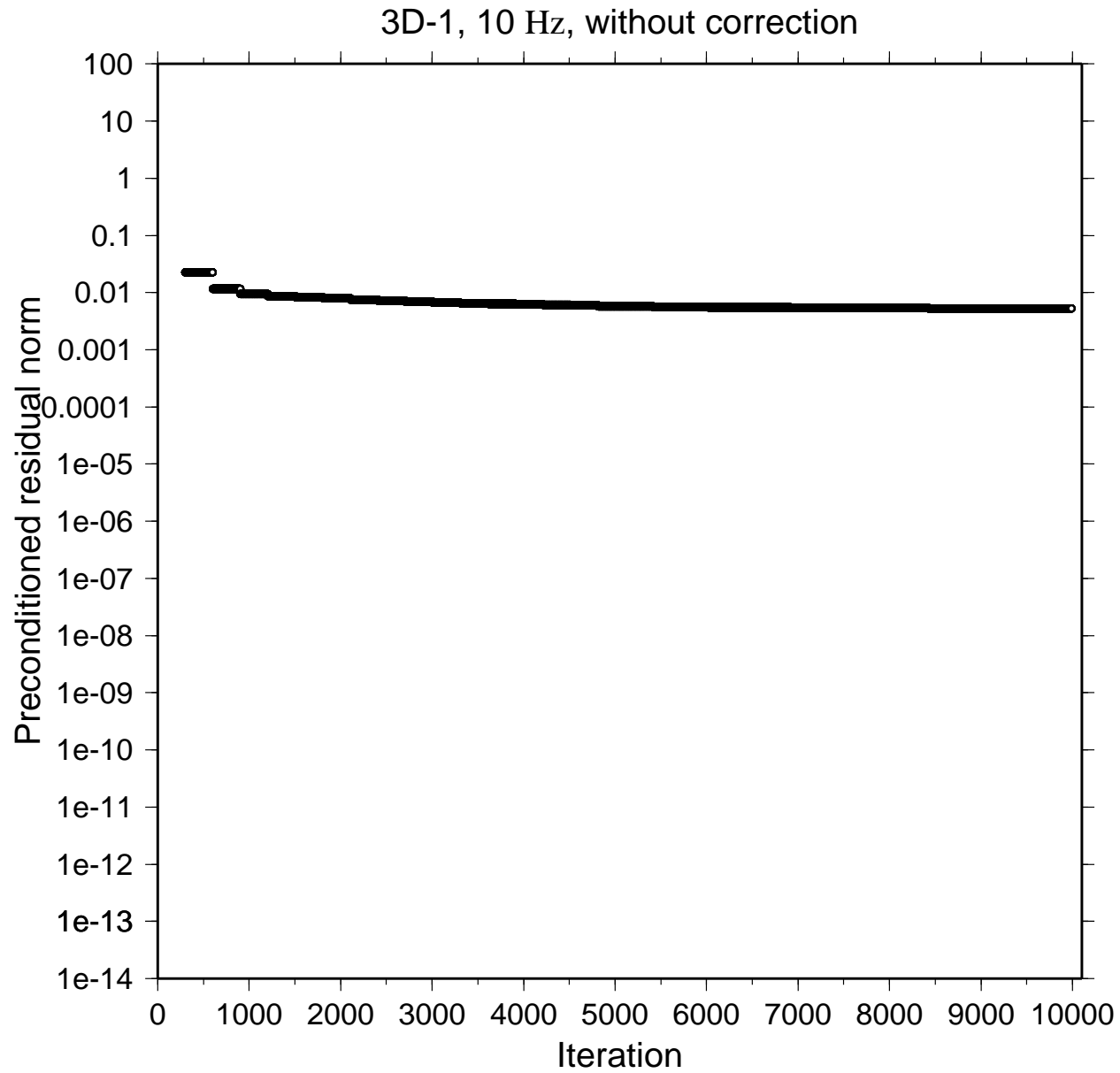
0.1 s, 10 s periods

Standard Finite-Element Modelling: Results

3D-1, 10 Hz, without correction

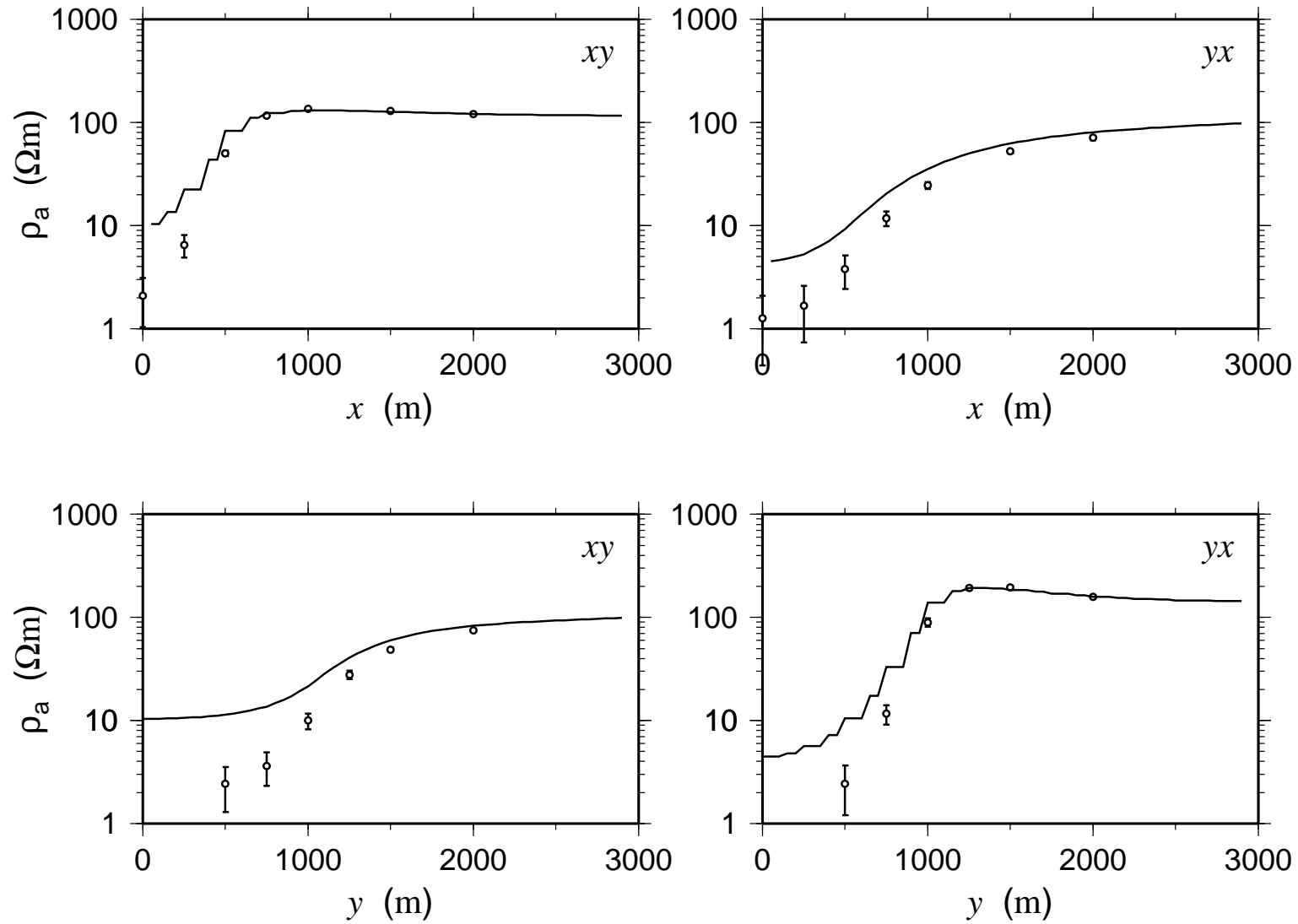


Standard Finite-Element Modelling: Results

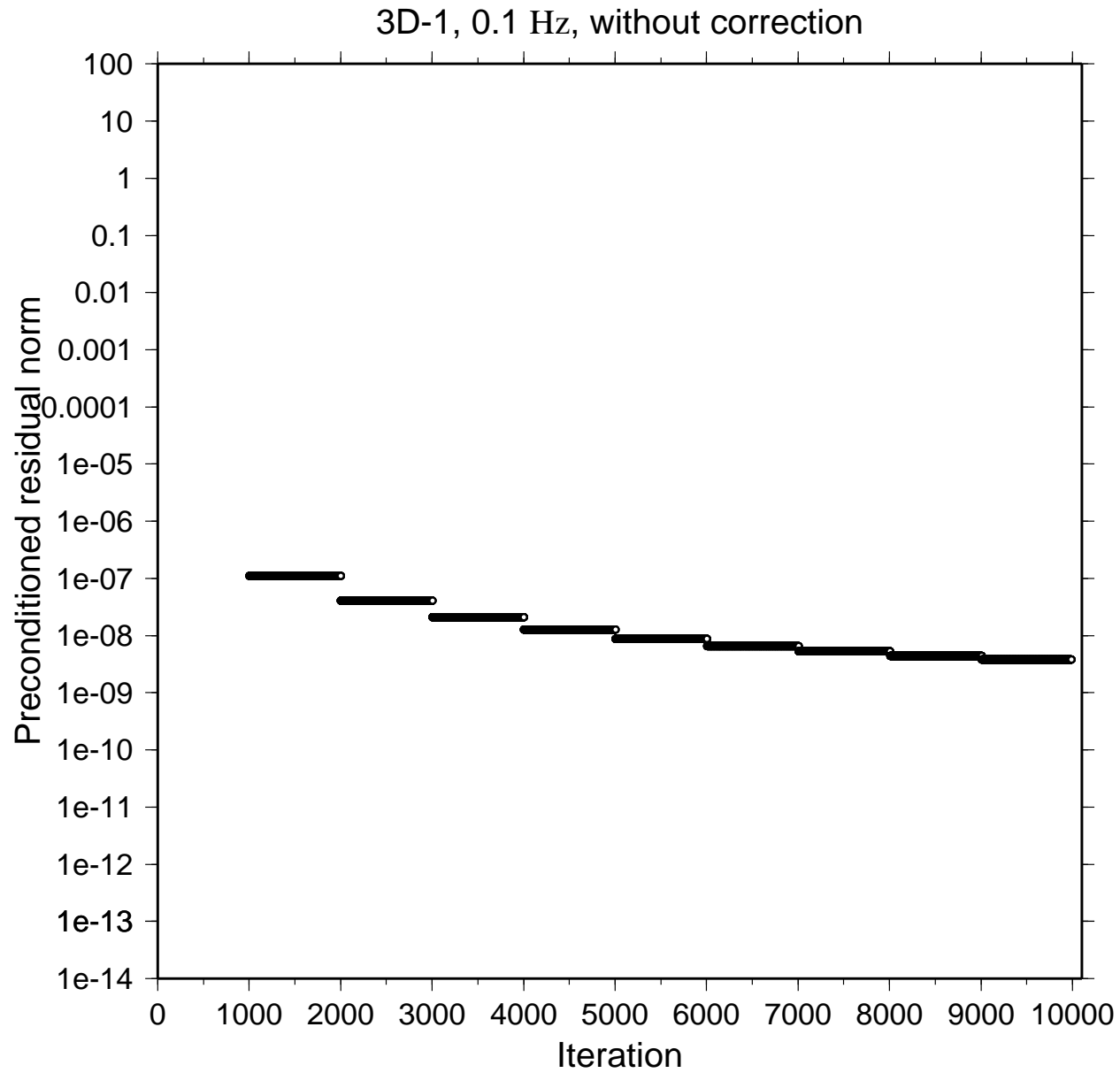


Standard Finite-Element Modelling: Results

3D-1, 0.1 Hz, without correction



Standard Finite-Element Modelling: Results



Finite-Element Modelling With Correction

- Electric field PDE:

$$\nabla \times \nabla \times \mathbf{E} - i\omega\mu_0\sigma\mathbf{E} = 0$$

- For low frequency, $\tilde{\mathbf{E}} + \nabla\phi$ for any ϕ is also effectively a solution of this PDE ...
- ... but not of $\nabla \cdot (\sigma\mathbf{E}) = 0$.
- Following Smith (1996), compute ϕ such that

$$\nabla \cdot (\sigma\nabla\phi) = -\nabla \cdot (\sigma\tilde{\mathbf{E}}),$$

and ‘correct’ the approximate electric field by:

$$\tilde{\mathbf{E}} \leftarrow \tilde{\mathbf{E}} + \nabla\phi.$$

Finite-Element Modelling With Correction

- Every so often in iterative solution process for edge-element solution of electric field PDE:
 - Standard finite-element solution of

$$\nabla \cdot (\sigma \nabla \phi) = -\nabla \cdot (\sigma \tilde{\mathbf{E}}),$$

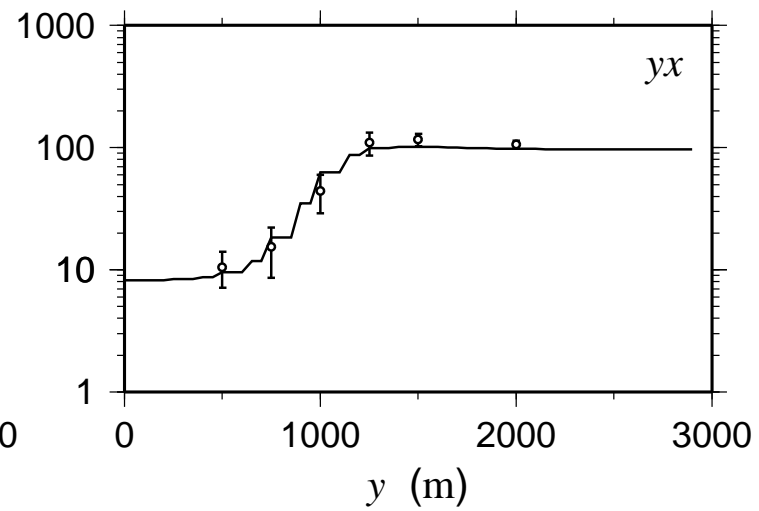
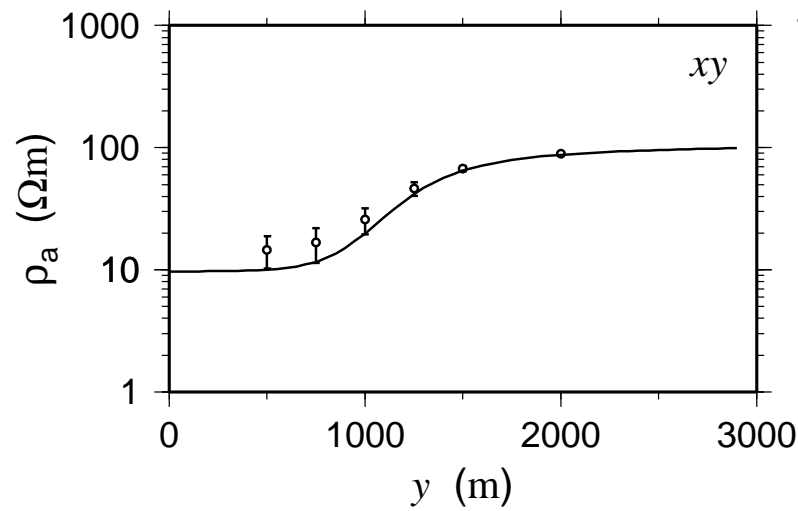
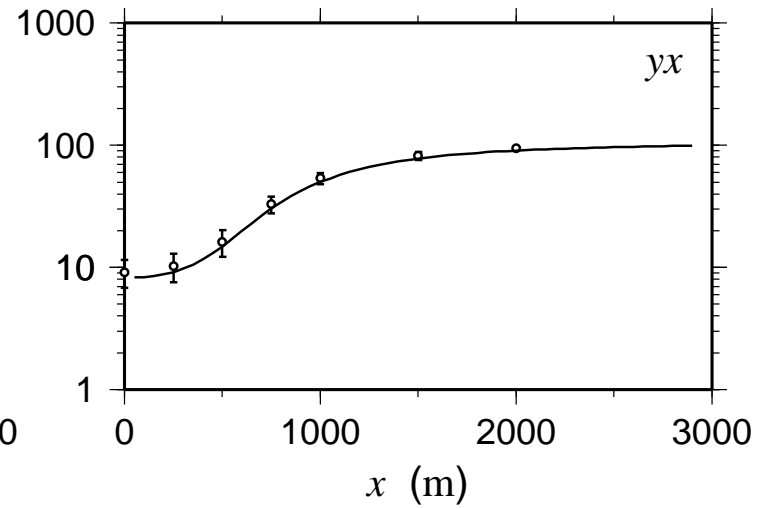
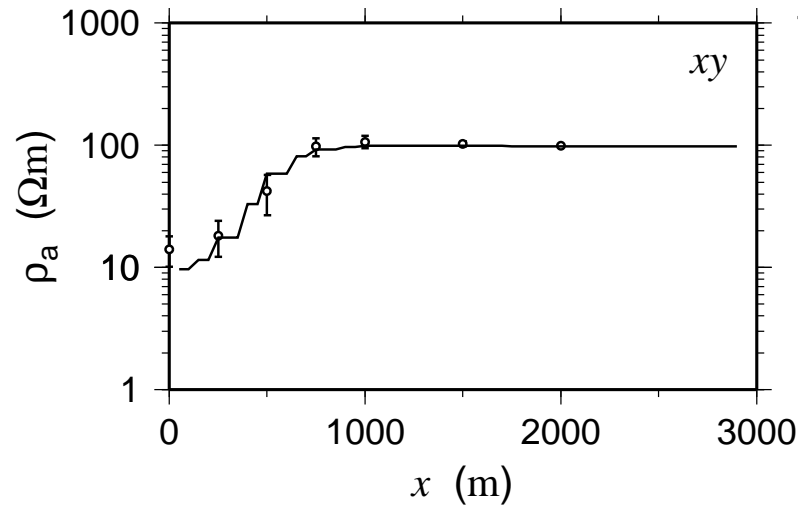
using nodal elements (tri-linear) for ϕ , Galerkin formulation, ILU preconditioned BCGSTAB.

- Correct approximate electric field by:

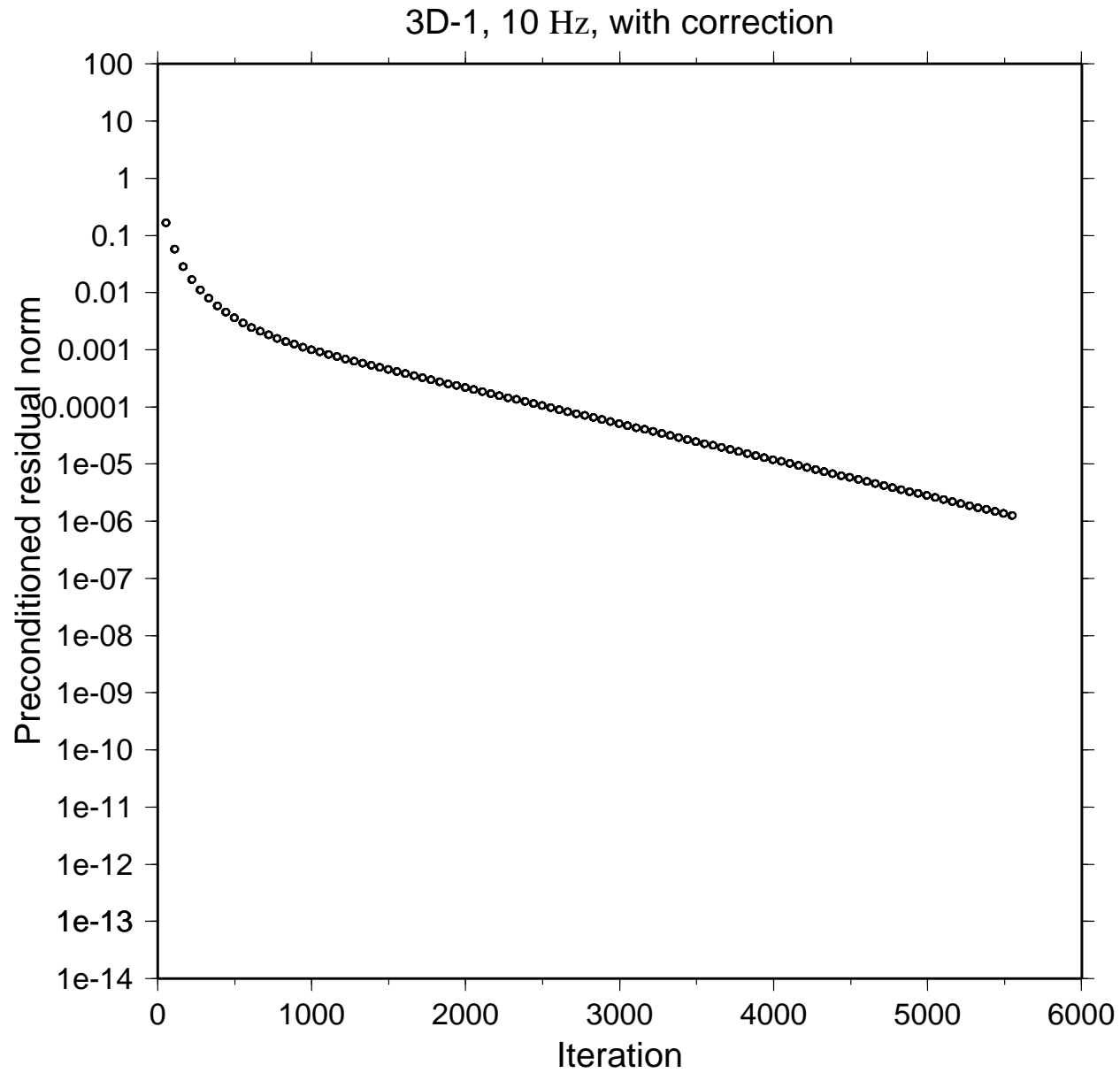
$$\tilde{\mathbf{E}} \leftarrow \tilde{\mathbf{E}} + \nabla \phi.$$

Finite-Element Modelling With Correction: Results

3D-1, 10 Hz, with correction

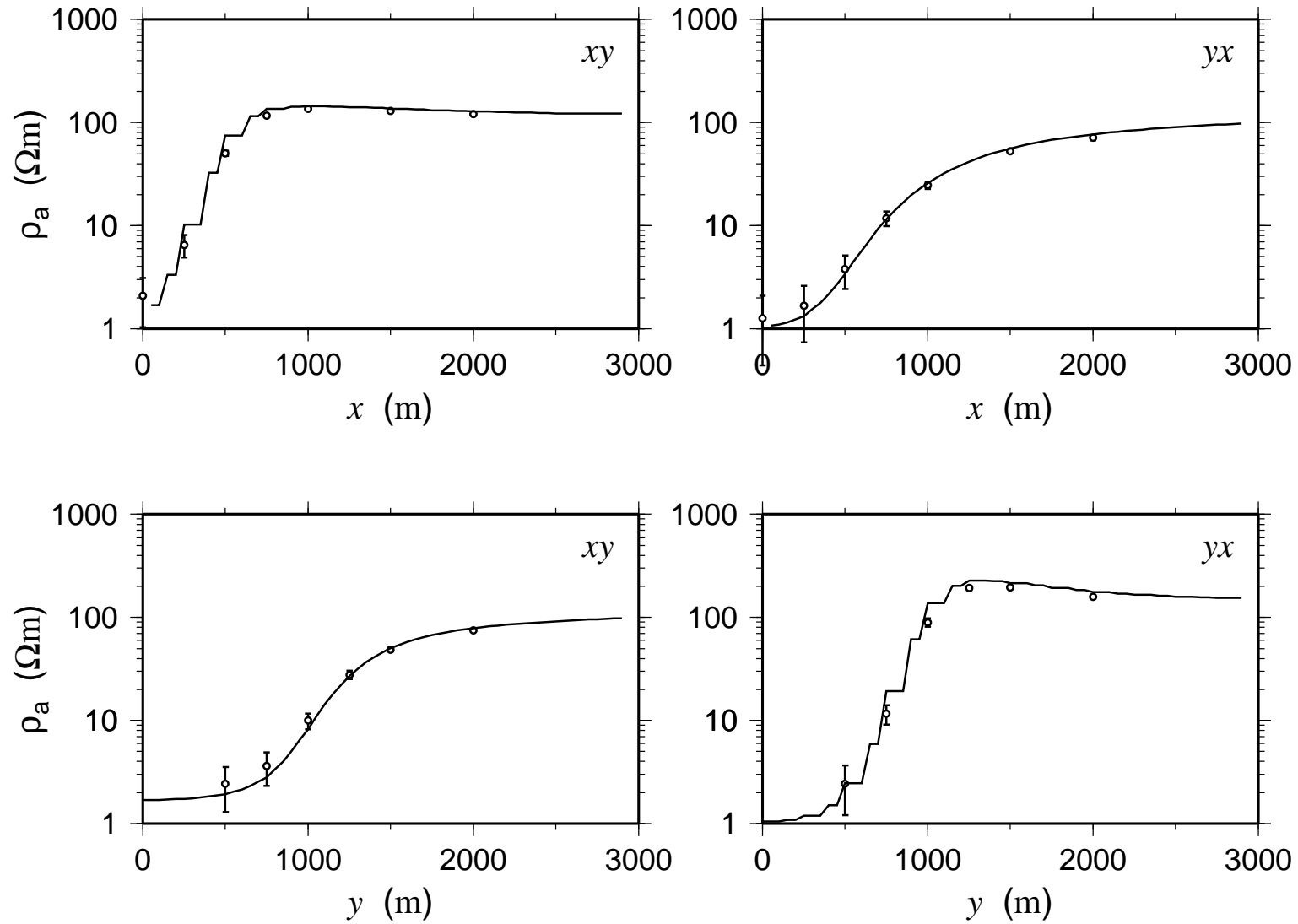


Finite-Element Modelling With Correction: Results

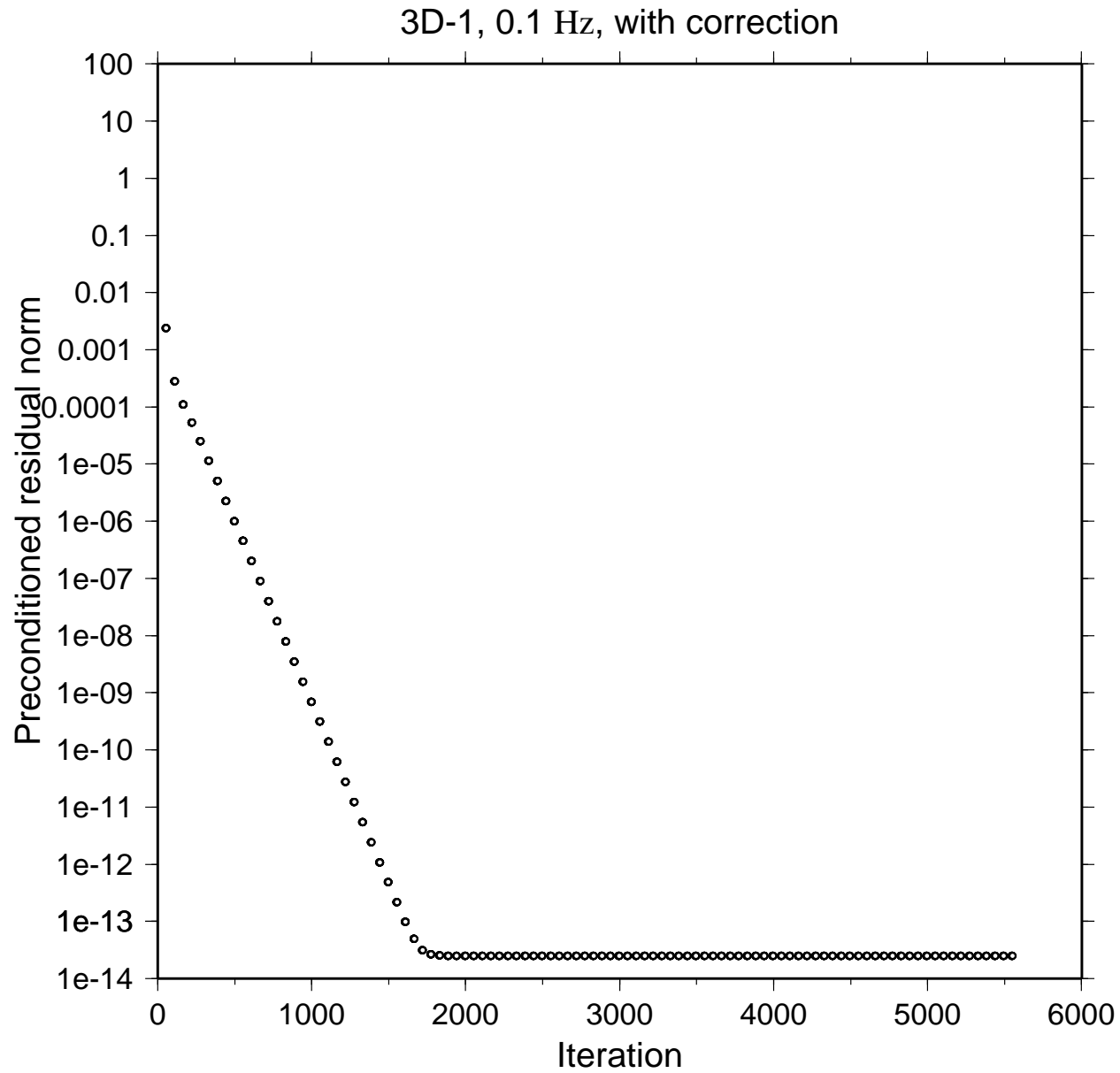


Finite-Element Modelling With Correction: Results

3D-1, 0.1 Hz, with correction

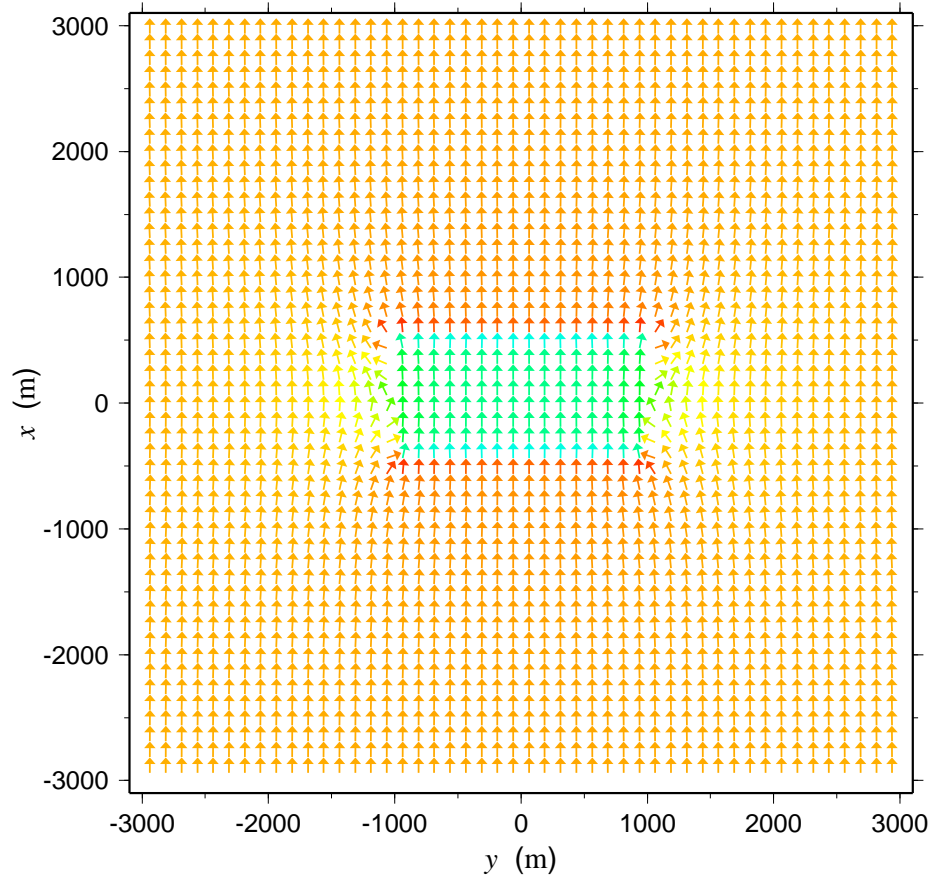


Finite-Element Modelling With Correction: Results

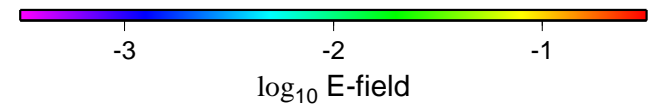
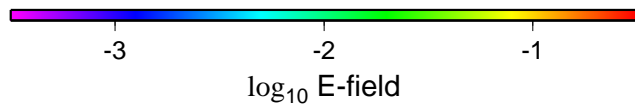
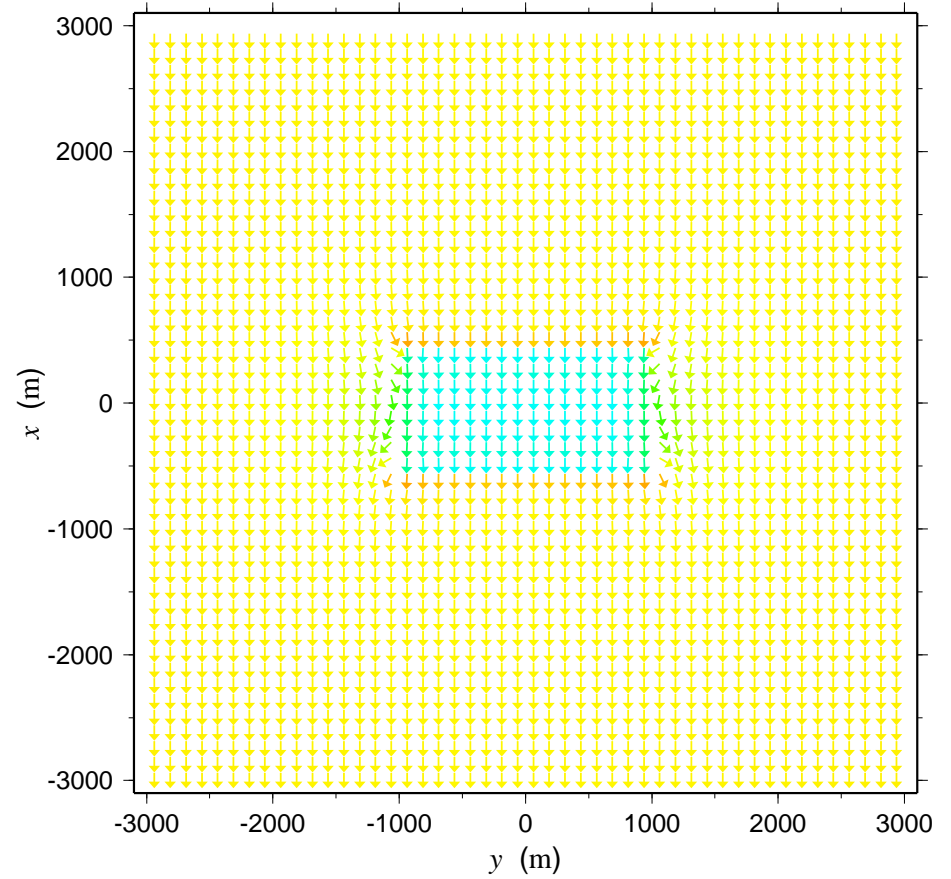


Finite-Element Modelling With Correction: Results

E-field; real; $z = 275$ m

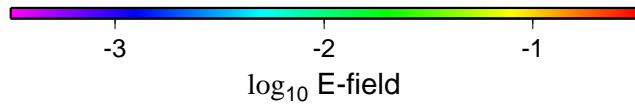
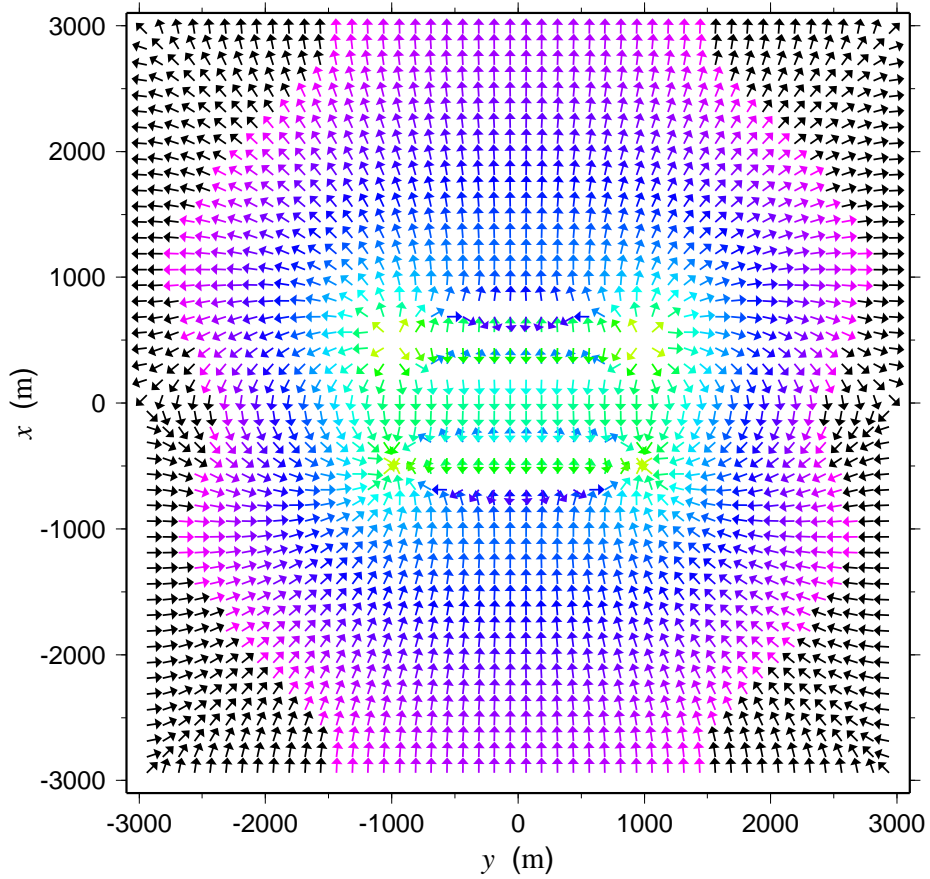


E-field; imaginary; $z = 275$ m

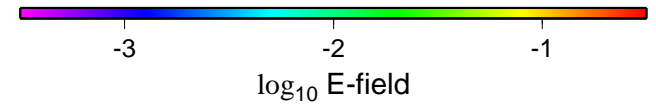
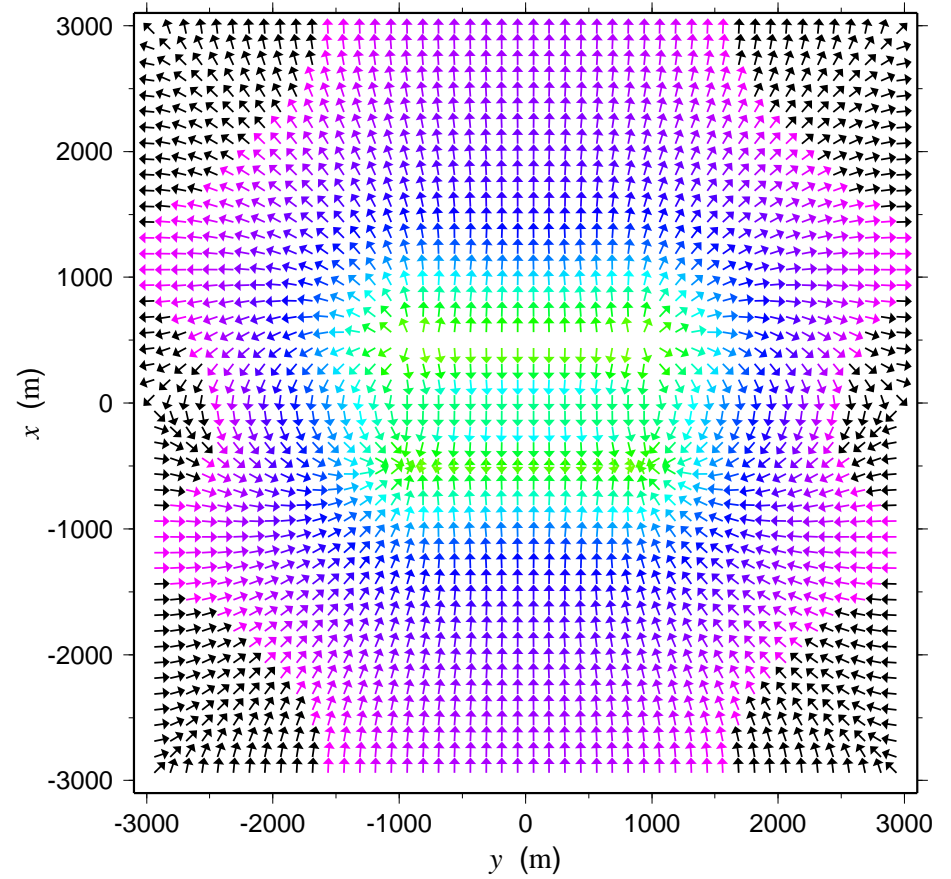


Finite-Element Modelling With Correction: Results

Correction E-field; real; $z = 275$ m



Correction E-field; imaginary; $z = 275$ m



Conclusions

★ A static divergence correction term, as introduced by Smith (1996) for a finite-difference solution, improves the performance of an edge-element finite-element solution for the electric field PDE.

(Edge elements were not thought to require such a correction term.)